

On stochastic 2D Navier Stokes equations and hydrodynamical models

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1 Introduction

- The evolution equations
- Random perturbation

2 Well posedness and apriori estimates

- The well posedness results
- Proof of the well posedness and apriori estimates

3 Further results

- Some control of time increments
- Large Deviations
- Support characterization
- Stochastic 2D Euler equation
- Stochastic 3D Navier Stokes equations

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Introduction

The Navier Stokes equations

D bounded domain of \mathbb{R}^2 , $x = (x_1, x_2)$,

$u(x, t) = (u^1(x, t), u^2(x, t))$ fluid velocity, $p(x, t)$ pressure

divergence: $\operatorname{div} u = \sum_{i=1,2} \partial_i u_i$

Laplace operator: $\Delta u = (\sum_{i=1,2} \partial_i^2 u^k, k = 1, 2)$ (Stokes operator if one adds the incompressibility condition $\operatorname{div} u = 0$ on D)

Find a pair (u, p) (u velocity, p pressure) such that

$$\partial_t u - \nu \Delta u + u \cdot \nabla u + \nabla p = f, \quad \operatorname{div} u = 0 \quad \text{in } D, \quad u = 0 \quad \text{on } \partial D$$

$\nu > 0$ viscosity, n outwards normal to ∂D and $f(x, t)$ external force

$$H = \{f \in [L^2(D)]^2 : \operatorname{div} f = 0 \text{ in } D \text{ and } f \cdot n = 0 \text{ on } \partial D\}$$

$V \equiv [H_0^1(D)]^2 \cap H$, $V \subset H$, $(H, | \cdot |)$ and $(V, \| \cdot \|)$ Hilbert spaces

Project on divergence free fields (integration by parts: if $\operatorname{div} u = 0$ then $(\nabla p, u) = 0$ if $\operatorname{div} u = 0$)

Introduction

The operators A and B

$A : V \rightarrow V'$ et $B : V \times V \rightarrow V'$ defined by:

$$\langle Au, v \rangle = \nu \sum_{j=1,2} \int_D \nabla u^j \cdot \nabla v^j dx$$

$$\langle B(u, v), w \rangle = \int_D [u \cdot \nabla v] w dx \equiv \sum_{i,j=1,2} \int_D u^j \partial_j v^i w^i dx, \quad \forall u, v, w \in V$$

Properties of A and B

$A = -\nu \Delta$ non-negative, unbounded, **self-adjoint** linear operator on H ,

$B : V \times V \rightarrow V'$ **bilinear continuous** $\forall u_1, u_2, u_3 \in V$

$$\langle B(u_1, u_2), u_3 \rangle = -\langle B(u_1, u_3), u_2 \rangle$$

(Proof: $\sum_{i,j} \int_D u^j \partial_j v^i w^i dx = -\sum_{i,j} \int_D v^i [w^i \partial_j u^j + u^j \partial_j w^i] dx$
for fixed i , $\sum_j \partial_j u^j = \operatorname{div} u = 0$)

Introduction

Interpolation space and B

- $V \subset \mathcal{L}^4(D) \subset H$ and for $u \in V$, $\|u\|_{\mathcal{L}^4(D)}^2 \leq |u| \|u\|$

(Proof: for real-valued functions f, g $\|fg\|_1 \leq \frac{1}{4} \|\partial_1 f\|_1 \|\partial_2 g\|_1$
with f^2 and g^2 , $\|f^2 g^2\|_1 \leq \|f \partial_1 f\|_1 \|g \partial_2 g\|_1$

Schwarz's inequality : $\|f^2 g^2\|_1 \leq \|f\|_2 \|\nabla f\|_2 \|g\|_2 \|\nabla g\|_2$; then
 $f = g$)

- For $\eta > 0$ there exists $C_\eta > 0$ such that

$$|\langle B(u_1, u_1), u_3 \rangle| \leq \eta \|u_1\|^2 + C_\eta |u_1|^2 \|u_3\|_{\mathcal{L}^4(D)}^4$$

(Proof: Hölder's inequality

$$|\int_D u_1 \nabla u_1 u_3| \leq \|u_1\|_{\mathcal{L}^4(D)} \|\nabla u_1\| \|u_3\|_{\mathcal{L}^4(D)} \leq \|u_1\|^{\frac{3}{2}} |u_1|^{\frac{1}{2}} \|u_3\|_{\mathcal{L}^4(D)}$$

Then Young's inequality with exponents $4/3$ and 4 yields

$$|\langle B(u_1, u_1), u_3 \rangle| \leq \frac{4\alpha}{3} \|u_1\|^2 + \frac{1}{4\alpha} |u_1|^2 \|u_3\|_{\mathcal{L}^4(D)}^4$$

- If $B(u) := B(u, u)$ then

$$|\langle B(u_1) - B(u_2), u_1 - u_2 \rangle| \leq \eta \|u_1 - u_2\|^2 + C_\eta |u_1 - u_2|^2 \|u_2\|_{\mathcal{L}^4(D)}^4$$

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Introduction

General framework

Project on divergence free functions, suppress the pressure $\operatorname{div} \nabla p = 0$
add a Coriolis term (replace the forcing term f by $f - Ru$ where

$R(u^1, u^2) = c_0(-u^2, u^1)$, c_0 constant. $\partial_t u - \nu \Delta u + u \cdot \nabla u + Ru = f$

Abstract setting $(H, |\cdot|)$ Hilbert, R linear continuous operator on H

A non negative, self-adjoint operator (unbounded) operator on H

$V = \operatorname{Dom}(A^{\frac{1}{2}})$; for $v \in V$ set $\|v\| = |A^{\frac{1}{2}} v|$

\mathcal{H} Banach space such that $V \subset \mathcal{H} \subset H$ and $\|v\|_{\mathcal{H}}^2 \leq K_0 |v| \|v\|$

$B : V \times V \rightarrow V'$ bilinear continuous such that $\forall u_1, u_2, u_3 \in V$

$$\langle B(u_1, u_2), u_3 \rangle = -\langle B(u_1, u_3), u_2 \rangle$$

for $\eta > 0$ there exists $C_\eta > 0$ such that

$$|\langle B(u_1, u_1), u_3 \rangle| \leq \eta \|u_1\|^2 + C_\eta |u_1|^2 \|u_3\|_{\mathcal{H}}^4$$

$$d_t u(t) + \left[Au(t) + B(u(t)) + Ru(t) \right] dt = \sigma(u(t)) dW_t, \quad u(0) \in H$$

Introduction

Other examples of evolution equations

$D = (0, l) \times (0, 1)$, $x = (x_1, x_2)$ spatial variable

p pressure, $\phi = (u, \theta, \beta)$ satisfy the coupled non-linear equations

$u \in \mathbb{R}^2$ velocity field, $\theta \in \mathbb{R}$ temperature field, $\beta \in \mathbb{R}^2$ magnetic field

ν, κ, η and S physical constants,

$$\begin{aligned} \frac{\partial}{\partial t} u + u \cdot \nabla u - \nu \Delta u + \nabla p \\ + \nabla \left(\frac{1}{2} |\beta|^2 \right) - S \beta \cdot \nabla \beta - \theta e_2 = \sigma_1(t, \phi) dW^1(t), \\ \frac{\partial}{\partial t} \theta + u \cdot \nabla \theta - \kappa \Delta \theta - u_2 = \sigma_2(t, \phi) dW^2(t), \\ \frac{\partial}{\partial t} \beta - \eta \Delta \beta + u \cdot \nabla \beta - \beta \cdot \nabla u = \sigma_3(t, \phi) dW^3(t), \end{aligned}$$

where Δ is the Laplace operator (Stokes operator after Leray projection)

Introduction

Examples of evolution equations - Conditions

$$\operatorname{div}(u) = \operatorname{div}(\beta) = 0$$

$$u = \theta = \beta_2 = \frac{\partial}{\partial x_2} \beta_1 = 0 \quad \text{on } x_2 \in \{0, 1\}$$

$$u, p, \theta, \beta, u_{x_1}, \theta_{x_1}, \beta_{x_1} \text{ period } l \text{ in } x_1$$

$H = L^2(D)^5$ with divergence, periodicity and boundary conditions

$V = H^1(D)^5$ with the same conditions

$V \hookrightarrow H = H' \hookrightarrow V' \quad \mathcal{H} = L^4(D)^5 \cap H$ and $\|u\|_{\mathcal{H}}^2 \leq K_0 |u| \|u\|$

$B(\phi) = (B_1(u, u) - SB_1(\beta, \beta), B_2(u, \theta), B_1(u, \beta) - B_1(\beta, u))$

$$\langle B_1(u, v), w \rangle = \int_D [u \cdot \nabla v] w dx \quad := \sum_{i,j=1,2} \int_D u_i \partial_i v_j w_j dx,$$

$$\langle B_2(u, \theta), \eta \rangle = \int_D [u \cdot \nabla \theta] \eta dx \quad := \sum_{i=1,2} \int_D u_i \partial_i \theta \eta dx.$$

Introduction

The Leray model for the 3D Navier-Stokes equation

Studied by A. Cheskidov, D. Holm, E. Olson & E. Titi

$D \subset \mathbb{R}^3$ bounded domain, A Stokes operator

$$\begin{aligned}\partial_t u - \nu \Delta u + v \cdot \nabla u + \nabla p &= f, \\ (1 - \alpha \Delta)v &= u, \quad \operatorname{div} u = 0, \quad \operatorname{div} v = 0 \quad \text{in } D, \\ v = u = 0 &\quad \text{on } \partial D.\end{aligned}$$

$G_\alpha = (1 - \alpha \Delta)^{-1}$ Green operator

$H = \{u \in [L^2(D)]^3 : \operatorname{div} u = 0 \text{ in } D \text{ and } u \cdot n = 0 \text{ on } \partial D\}$

As $H^{1/2}(D) \subset L^3(D)$, set $\mathcal{H} = [L^3(D)]^3 \cap H$. Since $H^1(D) \subset L^6(D)$ and $A^{\frac{1}{2}} G_\alpha$ is bounded on H , previous conditions fulfilled with $B_\alpha(u_1, u_2) := B(G_\alpha u_1, u_2)$

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Introduction

Noise W with trace class covariance Q

Covariance operator Q symmetric non-negative on H , $\text{Trace}(Q) < +\infty$

$H_0 = Q^{\frac{1}{2}}H$ Hilbert space $(\phi, \psi)_0 = (Q^{-\frac{1}{2}}\phi, Q^{-\frac{1}{2}}\psi)$, $\forall \phi, \psi \in H_0$,
embedding $i : H_0 \rightarrow H$ is Hilbert-Schmidt (hence compact), and

$$i i^* = Q$$

$W(t)$ H -valued Wiener process with covariance operator Q .

W is **Gaussian**, has independent time increments, for $s, t \geq 0$, $f, g \in H$,

$$\mathbb{E}(W(s), f) = 0 \quad \text{and} \quad \mathbb{E}(W(s), f)(W(t), g) = (s \wedge t)(Qf, g).$$

W has the representation

$$W(t) = \lim_{n \rightarrow \infty} W_n(t) \text{ in } L^2(\Omega; H) \text{ with } W_n(t) = \sum_{j=1}^n q_j^{1/2} \beta_j(t) e_j,$$

where β_j are **independent (real) Wiener** processes, $\{e_j\}$ is ONB in H of
eigen-elements of Q , with $Qe_j = q_j e_j$.

Introduction

The diffusion coefficient

$L_Q = \{S \in L(H_0, H) : SQ^{\frac{1}{2}} \text{ Hilbert Schmidt from } H \text{ to } H\}$,
 $\|S\|_{L_Q}^2 = \text{Trace}(S Q S^*)$, where S^* is the adjoint of S .

For any BON $\{\psi_k\}$ in H , the L_Q -norm can be written

$$\|S\|_{L_Q}^2 = \text{tr}([SQ^{1/2}][SQ^{1/2}]^*) = \sum_{k \geq 1} |SQ^{1/2}\psi_k|^2 = \sum_{k \geq 1} |[SQ^{1/2}]^*\psi_k|^2$$

$\sigma \in C([0, T] \times V) \rightarrow L_Q$

There exist constants K_i and L_i such that for $t \in [0, T]$, $\phi, \psi \in V$

$$|\sigma(t, \phi)|_{L_Q}^2 \leq K_0 + K_1|\phi|^2 + K_2\|\phi\|^2,$$

$$|\sigma(t, \phi) - \sigma(t, \psi)|_{L_Q}^2 \leq L_1|\phi - \psi|^2 + L_2\|\phi - \psi\|^2.$$

(in the above examples, σ may depend on the gradient of the solution)

Introduction

Rewriting the equations

With these notations, the above models (Bénard $\phi = (u, \theta, \beta)$, 2D Navier Stokes, "shell models" or 3D Leray Navier Stokes $\phi = u$) are written:

$$d\phi + [A\phi + B(\phi) + R\phi]dt = \sigma(\phi)dW(t), \quad \phi(0) = \xi \in H \quad (1)$$

ξ \mathcal{F}_0 -measurable, independent of W .

Solution means: (ϕ_t) adapted for (\mathcal{F}_t) and for $\psi \in D(A)$,

$$\begin{aligned} (\phi(t), \psi) - (\phi(0), \psi) + \int_0^t [(\phi(s), A\psi) + \langle B(\phi(s)), \psi \rangle \\ + (R\phi(s), \psi)] ds = \int_0^t (\sigma(\phi(s)) dW(s), \psi). \end{aligned}$$

Weak solution for analysts and **strong solution** for probabilists

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Well posedness and apriori bounds

The result

$\sigma(u)$ estimated in terms of u in V with constants K_2 and L_2

Theorem

Let $E|\xi|^4 < +\infty$. Then for K_2 small enough and $L_2 < 2$, there exists $C = C(K_i, L_i, T)$ such that the evolution equation has a unique solution $\phi \in X = C([0, T], H) \cap L^2(0, T; V)$. Furthermore,

$$E \left(\sup_{0 \leq t \leq T} |\phi(t)|^4 + \int_0^T \|\phi(t)\|^2 dt + \int_0^T \|\phi(t)\|_{\mathcal{H}}^4 dt \right) \leq C (1 + E|\xi|^4)$$

- Ferrario 1997 (Boussinesq equation) $\phi = (u, \theta)$, Barbu-Da Prato 2007 (MHD equation) $\phi = (u, \beta)$ for additive noise
- Sritharan-Sundar (Navier Stokes) $\phi = u$, Duan-M (Boussinesq) $\phi = (u, \theta)$, Chueshov-M., Manna-Shritharan-Sundar (shell models)

The well posedness results

General stochastic controlled equations

Set of controls

$$\mathcal{S}_M = \left\{ h \in L^2([0, T], H_0) : \int_0^T |h(s)|_0^2 ds \leq M \right\}$$

$$\mathcal{A}_M = \{ h \text{ } (\mathcal{F}_t) \text{ predictable} : h(\omega) \in \mathcal{S}_M \text{ a.s.} \}$$

First idea: shift W a random element of \mathcal{A}_M and use Girsanov

Need more general stochastic controls $\tilde{\sigma} \in C([0, T] \times V; L(H_0, H))$

there exist constants $\tilde{K}_{\mathcal{H}}$, \tilde{K}_i , and \tilde{L}_j , for $i = 0, 1$ and $j = 1, 2$ such that for $u, v \in V$, $t \in [0, T]$,

$$\begin{aligned} |\tilde{\sigma}(t, u)|_{L(H_0, H)}^2 &\leq \tilde{K}_0 + \tilde{K}_1 |u|^2 + \tilde{K}_{\mathcal{H}} \|u\|_{\mathcal{H}}^2, \\ |\tilde{\sigma}(t, u) - \tilde{\sigma}(t, v)|_{L(H_0, H)}^2 &\leq \tilde{L}_1 |u - v|^2 + \tilde{L}_2 \|u - v\|^2. \end{aligned}$$

$\tilde{R} : [0, T] \times H \mapsto H$ is continuous global growth and Lipschitz

The well posedness results

The result for stochastic controlled equation

Recall that K_2 and L_2 are the growth and Lipschitz constants in front of the V norm.

Theorem

(Chueshov-M.) Suppose that either $\tilde{\sigma} = \sigma$, or that $\tilde{\sigma}$ satisfies the above conditions. Let $M > 0$, h such that $\int_0^T |h(s)|_0^2 ds \leq M$ a.s., suppose that $K_2 \leq \kappa_2$ and $L_2 \leq \lambda_2$ for small κ_2, λ_2 . Let $u_h(0) = \xi$ be in \mathcal{F}_0 s.t. $E|\xi|^4 < +\infty$.

$$du_h + [Au_h + B(u_h, u_h) + \tilde{R}u_h]dt = \sigma(u_h)dW(t) + \tilde{\sigma}(u_h)h dt$$

has a unique solution in $X = C([0, T], H) \cap L^2(0, T; V)$ s.t.

$$\mathbb{E} \left(\sup_{0 \leq t \leq T} |u_h(t)|^4 + \int_0^T \|u_h(t)\|^2 dt \right) \leq C(M, \kappa_2, \lambda_2) (1 + E|\xi|^4).$$

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Proof of the well posedness and apriori estimates

Galerkin approximations

$F : [0, T] \times V \rightarrow V'$ be defined by

$$F(t, u) = -Au - B(u, u) - \tilde{R}(t, u), \quad \forall t \in [0, T], \forall u \in V.$$

$$\langle F(u) - F(v), u - v \rangle \leq -(1 - \eta) \|u - v\|^2 + (R_1 + C_\eta \|v\|_{\mathcal{H}}^4) |u - v|^2.$$

$\{\varphi_n\}_{n \geq 1}$ ONB of H such that $\varphi_n \in \text{Dom}(A)$. For $n \geq 1$, let $H_n = \text{span}(\varphi_1, \dots, \varphi_n) \subset \text{Dom}(A)$, $P_n : H \rightarrow H_n$ orthogonal projection from H onto H_n , $\sigma_n = P_n \sigma$ and $\tilde{\sigma}_n = P_n \tilde{\sigma}$

For $h \in \mathcal{A}_M$, evolution equation on (n -dim. space) H_n defined by $u_{n,h}(0) = P_n \xi$:

$$du_{n,h}(t) = [F(u_{n,h}(t)) + \tilde{\sigma}(u_{n,h}(t))h(t)] dt + \sigma(u_{n,h}(t)) dW_n(t)$$

and $W_n = \sum_{1 \leq j \leq n} \sqrt{q_j} \beta_j(t) e_j$. For $k = 1, \dots, n$

$$\begin{aligned} d(u_{n,h}(t), \varphi_k) &= [\langle F(u_{n,h}(t)), \varphi_k \rangle + (\tilde{\sigma}(u_{n,h}(t))h(t), \varphi_k)] dt \\ &\quad + \sum_{j=1}^n q_j^{\frac{1}{2}} (\sigma(u_{n,h}(t)) e_j, \varphi_k) d\beta_j(t). \end{aligned}$$

Proof of the well posedness and apriori estimates

Explosion time for the Galerkin approximation

B is bilinear and F locally Lipschitz. There exists a maximal solution $u_{n,h}$ and a **stopping time** $\tau_{n,h}$ such that the evolution equation for $u_{n,h}$ holds for $t < \tau_{n,h}$ and as $t \uparrow \tau_{n,h} < T$, $|u_{n,h}(t)| \rightarrow \infty$.

Prove that $\tau_{n,h} = T$ a.s.

Proposition

Fix $M > 0$, $T > 0$, $h \in \mathcal{A}_M$, $0 \leq K_2 \leq \bar{K}_2$ and $\xi \in L^{2p}(\Omega, H)$.

$$|\tilde{\sigma}(t, u)|_{L(H_0, H)}^2 \leq \tilde{K}_0 + \tilde{K}_1 |u|^2 + \tilde{K}_2 \|u\|^2, \quad \forall t \in [0, T], \forall u \in V,$$

For $p \geq 1$ there exists $\bar{K}_2 = \bar{K}_2(p, T, M)$ and $C = C(p, K_2, M, T)$ such that for $0 \leq K_2 < \bar{K}_2$: $\tau_{n,h} = T$ a.s. and a modification of the solution $u_{n,h} \in C([0, T], H_n)$

$$\begin{aligned} \sup_n \mathbb{E} \left(\sup_{0 \leq t \leq T} |u_{n,h}(t)|^{2p} + \int_0^T \|u_{n,h}(s)\|^2 |u_{n,h}(s)|^{2(p-1)} ds \right) \\ \leq C(\mathbb{E}|\xi|^{2p} + 1) \end{aligned}$$

Proof of the well posedness and a priori estimates

$$\langle B(u, u), u \rangle = 0$$

Fix $N > 0$ and $\tau_N = \inf\{t : |u_{n,h}(t)| \geq N\} \wedge T$. Itô's formula for $|\cdot|^2$ and $\langle B(u, u), u \rangle = 0$,

$$\begin{aligned} |u_{n,h}(t \wedge \tau_N)|^2 &= |P_n \xi|^2 + 2 \int_0^{t \wedge \tau_N} (\sigma_n(u_{n,h}(s)) dW_n(s), u_{n,h}(s)) \\ &\quad - 2 \int_0^{t \wedge \tau_N} \|u_{n,h}(s)\|^2 ds + \int_0^{t \wedge \tau_N} |\sigma_n(u_{n,h}(s)) \Pi_n|_{L_Q}^2 ds \\ &\quad - 2 \int_0^{t \wedge \tau_N} (\tilde{R}(u_{n,h}(s)) - \tilde{\sigma}_n(u_{n,h}(s))h(s), u_{n,h}(s)) ds \end{aligned}$$

Itô's formula for $z \rightarrow z^p$ with $p \geq 2$ and $z = |u_{n,h}(t \wedge \tau_N)|^2$ plus conditions on coefficients

Proof of the well posedness and apriori estimates

Generalized Gronwall's lemma

Lemma

Let X, Y, I and φ be non-negative processes and Z be a non-negative integrable random variable. Assume that I is non-decreasing and there exist non-negative constants $C, \alpha, \beta, \gamma, \delta$ with $\int_0^T \varphi(s) ds \leq C$ a.s., $2\beta e^C \leq 1$, $2\delta e^C \leq \alpha$ and such that for $0 \leq t \leq T$,

$$X(t) + \alpha Y(t) \leq Z + \int_0^t \varphi(r) X(r) dr + I(t), \text{ a.s.},$$

$$\mathbb{E}(I(t)) \leq \beta \mathbb{E}(X(t)) + \gamma \int_0^t \mathbb{E}(X(s)) ds + \delta \mathbb{E}(Y(t)) + \tilde{C},$$

where $\tilde{C} > 0$ is a constant. If $X \in L^\infty([0, T] \times \Omega)$, then we have

$$\mathbb{E}[X(t) + \alpha Y(t)] \leq 2 \exp(C + 2t\gamma e^C) (\mathbb{E}(Z) + \tilde{C}), \quad t \in [0, T].$$

Proof of the well posedness and a priori estimates

using the generalized Gronwall lemma

Apply the generalized Gronwall lemma to

$$X(t) = \sup_{s \leq t \wedge \tau_N} |u_{n,h}(t \wedge \tau_N)|^{2p},$$

$$Y(t) = \int_0^{t \wedge \tau_N} |u_{n,h}(r)|^{2(p-1)} \|u_{n,h}(r)\|^2 dr, \text{ for } t \in [0, T]$$

$$X(t) + pY(t) \leq Z(|\xi|^{2p}, T, M) + \int_0^{t \wedge \tau_N} \varphi(r)X(r)dr + I(t)$$

where $\int_0^T \varphi(s)ds \leq C(T, M)$ a.s.,

$$I(t) = \sup_{0 \leq s \leq t} |J(s)|,$$

$$J(t) = 2p \left| \int_0^{t \wedge \tau_N} (\sigma_n(u_{n,h}(r)) dW_n(r), u_{n,h}(r) |u_{n,h}(r)|^{2(p-1)}) \right|$$

Use the BDG inequality: For β small enough and then K_2 small enough, there exist C, \tilde{C} such that for $t \in [0, T]$,

$$\mathbb{E}[X(t) + Y(t)] \leq 2 \exp(CM + \tilde{C}te^{CM}) (\mathbb{E}Z(|\xi|^{2p}, T, M) + C(p, T))$$

Proof of the well posedness and apriori estimates

Weakly converging subsequences

$N \rightarrow \infty$, $\tau_N \rightarrow \tau_{n,h}$ and **upper estimate above independent of N and n** .

Hence on $\tau_{n,h} < T$, $\sup_{s \leq \tau_N} |u_{n,h}(s)| = +\infty$. Contradiction.

Let $\mathbb{E}|\xi|^4 < \infty$ and use interpolation $\|u\|_{\mathcal{H}}^4 \leq C|u|^2\|u\|^2$.

Set $\Omega_T = [0, T] \times \Omega$. There exists a **subsequence of $u_{n,h}$** and

$$u_h \in \mathcal{X} := L^2(\Omega_T, V) \cap L^4(\Omega_T, \mathcal{H}) \cap L^4(\Omega, L^\infty([0, T], H)),$$

$F_h \in L^2(\Omega_T, V')$ and $S_h, \tilde{S}_h \in L^2(\Omega_T, L_Q)$, and of r.v.

$\tilde{u}_h(T) \in L^2(\Omega, H)$ such that:

- (i) $u_{n,h} \rightarrow u_h$ weakly in $L^2(\Omega_T, V)$,
- (ii) $u_{n,h} \rightarrow u_h$ weakly in $L^4(\Omega_T, \mathcal{H})$,
- (iii) $u_{n,h}$ is weak star converging to u_h in $L^4(\Omega, L^\infty([0, T], H))$,
- (iv) $u_{n,h}(T) \rightarrow \tilde{u}_h(T)$ weakly in $L^2(\Omega, H)$,
- (v) $F(u_{n,h}) \rightarrow F_h$ weakly in $L^2(\Omega_T, V')$,
- (vi) $\sigma_n(u_{n,h})\Pi_n \rightarrow S_h$ weakly in $L^2(\Omega_T, L_Q)$,
- (vii) $\tilde{\sigma}_n(u_{n,h})h \rightarrow \tilde{S}_h$ weakly in $L^{\frac{4}{3}}(\Omega_T, H)$

Proof of the well posedness and a priori estimates

Identification of the limit u_h

Pass evolution equation to the limit (inner product with $f_k(t)\varphi_j$)
 $f_k \in H^1(-\delta, T + \delta)$ such that $\|f_k\|_\infty = 1$, $f_k = 1$ on $(-\delta, t - \frac{1}{k})$ and
 $f_k = 0$ on $(t, T + \delta)$ implies

$$0 = (\xi - u_h(t), \varphi_j) + \int_0^t (S_h(s)dW(s), \varphi_j) + \int_0^t \langle F_h(s) + \tilde{S}_h(s), \varphi_j \rangle ds$$

j arbitrary and for $f = 1_{(-\delta, T+\delta)}$ yields $u_h(T) = \tilde{u}_h(T)$ where

$$u_h(t) = \xi + \int_0^t S_h(s)dW(s) + \int_0^t F_h(s)ds + \int_0^t \tilde{S}_h(s)ds$$

Prove that $ds \otimes d\mathbb{P}$ a.s.

$$S_h(s) = \sigma(u_h(s)), F_h(s) = F(u_h(s)) \text{ and } \tilde{S}_h(s) = \tilde{\sigma}(u_h(s)) h(s)$$

Proof of the well posedness and apriori estimates

Identification of the limit u_h

Let $v \in \mathcal{X} = L^4(\Omega_T, \mathcal{H}) \cap L^4(\Omega, L^\infty([0, T], H)) \cap L^2(\Omega_T, V)$. Suppose that $L_2 < 2$ and let $0 < \eta < \frac{2-L_2}{3}$; set

$$r(t) = \int_0^t \left[2R_1 + 2C_\eta \|v(s)\|_{\mathcal{H}}^4 + L_1 + 2\sqrt{\tilde{L}_1} |h(s)|_0 + \frac{\tilde{L}_2}{\eta} |h(s)|_0^2 \right] ds,$$

Apply Itô's formula to $|u(t)|^2 e^{-r(t)}$ for $u = u_h$ and $u = u_{n,h}$ leads to prove that upper estimate $\liminf_n X_n$, where

$$X_n = \mathbb{E} \int_0^T e^{-r(s)} \left[-r'(s) \left\{ |u_{n,h}(s) - v(s)|^2 + 2(u_{n,h}(s) - v(s), v(s)) \right\} \right. \\ \left. + 2\langle F(u_{n,h}(s)), u_{n,h}(s) \rangle + |\sigma_n(u_{n,h}(s)) \Pi_n|_{L_Q}^2 + 2(\tilde{\sigma}(u_{n,h}(s))h(s), u_{n,h}(s)) \right] ds$$

Some coercivity and monotonicity properties (only valid in 2D) based on

$$\langle F(u) - F(v), u - v \rangle \leq -(1 - \eta) \|u - v\|^2 + (R_1 + C_\eta \|v\|_{\mathcal{H}}^4) |u - v|^2$$

imply

Proof of the well posedness and a priori estimates

Identification of the limit u_h

For any $v \in \mathcal{X}$,

$$\mathbb{E} \int_0^T e^{-r(s)} \left\{ -r'(s) |u_h(s) - v(s)|^2 + 2 \langle F_h(s) - F(v(s)), u_h(s) - v(s) \rangle \right. \\ \left. + |S_h(s) - \sigma(v(s))|_{L^Q}^2 + 2 \left(\tilde{S}_h(s) - \tilde{\sigma}(v(s))h(s), u_h(s) - v(s) \right) \right\} ds \leq 0.$$

$v = u_h \in \mathcal{X}$ implies $S_h(s) = \sigma(u_h(s))$

$\tilde{v} \in L^\infty([0, T] \times \Omega)$ and $v_\lambda = u_h - \lambda \tilde{v}$ previous result with v_λ and r_λ

Let $\lambda \rightarrow 0$ and divide the inequality for v_λ and r_λ by $\lambda > 0$ (resp.

$\lambda < 0$) yields

$$\mathbb{E} \int_0^T e^{-r_0(s)} \left[\langle F_h(s) - F(u_h(s)), \tilde{v}(s) \rangle + (\tilde{S}_h(s) - \tilde{\sigma}(u_h(s))h(s), \tilde{v}(s)) \right] ds = 0$$

Hence $u_h(t) = \xi + \int_0^t \sigma(u_h(s)) dW(s) + \int_0^t [F(u_h(s)) + \tilde{\sigma}(u_h(s))h(s)] ds$

Proof of the well posedness and apriori estimates

Time regularity of u_h ; uniqueness

- For $\delta > 0$, $e^{-\delta A}$ maps H to V and V' to H . For $\delta > 0$

$$e^{-\delta A} u_h \in C([0, T], H) \text{ a.s.}$$

Set $G_\delta = Id - e^{-\delta A}$, apply Itô's formula to $|G_\delta u_h(t)|^2$

As $\delta \rightarrow 0$,

$$\mathbb{E} \left(\sup_{0 \leq t \leq T} |G_\delta(u_h(t))|^2 \right) = 0$$

- Let $v \in C([0, T], H)$ be another solution, set $U = u_h - v$ and $\tau_N = \inf\{t \geq 0 : |u_h(t)| \geq N\} \wedge \inf\{t \geq 0 : |v(t)| \geq N\} \wedge T$
Apply Itô's formula for

$$\exp \left(-a \int_0^{s \wedge \tau_N} \|u_h(r)\|_{\mathcal{H}}^4 dr \right) |U(s \wedge \tau_N)|^2$$

Apply the extended Gronwall lemma

Proof of the well posedness and apriori estimates

Time regularity of u_h ; uniqueness

- For $\delta > 0$, $e^{-\delta A}$ maps H to V and V' to H . For $\delta > 0$

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Apply the extended Gronwall lemma

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Some "weak" control of time increments

Given $M > 0$, $N > 0$, $h \in \mathcal{A}_M$, let u_h denote the solution to

$$du_h(t) + [Au_h(t) + B(u_h(t)) + \tilde{R}(t, u_h(t))] dt = \sigma(t, u_h(t)) dW(t) + \tilde{\sigma}(t, u_h(t)) h(t) dt$$

$$G_N(t) = \left\{ \omega : \left(\sup_{0 \leq s \leq t} |u_h(s)(\omega)|^2 \right) \vee \left(\int_0^t \|u_h(s)(\omega)\|^2 ds \right) \leq N \right\}.$$

Lemma

Under the conditions of the well-posedness theorem, if the initial condition $\xi \in L^4(\Omega; H)$, there exists a positive constant C such that for any $h \in \mathcal{A}_M$, if $\psi_n : [0, T] \rightarrow [0, T]$ is a Borel function with $s \leq \psi_n(s) \leq s + c2^{-n}$ or $s - c2^{-n} \leq \psi_n(s) \leq s$

$$I_n(h) := \mathbb{E} \left[\mathbf{1}_{G_N(T)} \int_0^T |u_h(s) - u_h(\psi_n(s))|^2 ds \right] \leq C 2^{-\frac{n}{2}}.$$

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Large deviation principles

Small perturbation

- Evolution equation perturbed by a "small" parameter ε

$$d\phi^\varepsilon + [A\phi^\varepsilon + B(\phi^\varepsilon) + R\phi^\varepsilon] dt = \sqrt{\varepsilon} \sigma(\phi^\varepsilon) dW(t),$$

$\phi(0) = \xi \in H$. Solution exists if $\varepsilon \leq \varepsilon_0$ for all K ;

- Prove a LDP as $\varepsilon \rightarrow 0$ in $X := C([0, T]; H) \cap L^2((0, T); V)$

$$\|\phi\|_X = \left\{ \sup_{0 \leq s \leq T} |\phi(s)|^2 + \int_0^T \|\phi(s)\|^2 ds \right\}^{\frac{1}{2}}.$$

For every closed (resp. open) set F (resp. G) of X :

$$\limsup_{\varepsilon \rightarrow 0} \varepsilon \log \mathbb{P}(\phi^\varepsilon \in F) \leq - \inf \{I(\psi), \psi \in F\}.$$

$$\liminf_{\varepsilon \rightarrow 0} \varepsilon \log \mathbb{P}(\phi^\varepsilon \in G) \geq - \inf \{I(\psi), \psi \in G\}.$$

with a good rate function $I : X \rightarrow [0, +\infty]$, i.e., level sets $\{\psi \in X : I(\psi) \leq M\}$ are compact subsets of X .

Large deviation principles

Small perturbation

- Evolution equation perturbed by a "small" parameter ε

$$d\phi^\varepsilon + [A\phi^\varepsilon + B(\phi^\varepsilon) + R\phi^\varepsilon] dt = \sqrt{\varepsilon} \sigma(\phi^\varepsilon) dW(t),$$

$\phi(0) = \xi \in H$. Solution exists if $\varepsilon \leq \varepsilon_0$ for all K_i

- Prove a LDP as $\varepsilon \rightarrow 0$ in $X := C([0, T]; H) \cap L^2((0, T); V)$

$$\|\phi\|_X = \left\{ \sup_{0 \leq s \leq T} |\phi(s)|^2 + \int_0^T \|\phi(s)\|^2 ds \right\}^{\frac{1}{2}}.$$

For every closed (resp. open) set F (resp. G) of X :

$$\limsup_{\varepsilon \rightarrow 0} \varepsilon \log \mathbb{P}(\phi^\varepsilon \in F) \leq - \inf \{I(\psi), \psi \in F\}.$$

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with a good rate function $I : X \rightarrow [0, +\infty]$, i.e., level sets $\{\psi \in X : I(\psi) \leq M\}$ are compact subsets of X .

Formulation of LDP

Statement of the LDP - Small perturbation

Let $h \in L^2([0, T], H_0)$; let $\phi_h = G^0(\int_0^\cdot h(s)ds) = \mathcal{G}^0(h)$ denote the **deterministic controlled equation**

$$d\phi_h(t) + [A\phi_h(t) + B(\phi_h(t)) + R\phi_h(t)]dt = \sigma(\phi_h(t))h(t)dt, \quad \phi_h(0) = \xi$$

Theorem

(Chueshov-M.) Let $\xi \in H$ and $K_2 = L_2 = 0$. The solution ϕ^ε of

$$d\phi^\varepsilon + [A\phi^\varepsilon + B(\phi^\varepsilon) + R\phi^\varepsilon]dt = \sqrt{\varepsilon} \sigma(\phi^\varepsilon)dW(t), \quad \phi^\varepsilon(0) = \xi \in H.$$

satisfies a **LDP** in $X = C([0, T]; H) \cap L^2(0, T; V)$ with good r.f.

$$I_\xi(\psi) = \inf \{ \|h\|_{L^2([0, T], H_0)}^2 / 2 : h \in L^2(0, T; H_0), \psi = \mathcal{G}^0(h) \}$$

Proved for 2D NS (Shritharan-Sundar), Boussinesq (Duan-M.), small perturbed shell models (Manna, Shritharan & Sundar)

Proof of the LDP

Weak convergence

The main step is the following:

Proposition

Suppose $K_2 = L_2 = 0$, let ξ be \mathcal{F}_0 -measurable such that $E|\xi|_H^4 < +\infty$. Let h_ε converge to h_0 in distribution as random elements taking values in \mathcal{A}_M (predictable elements which a.s. belong to the ball S_M of the RKHS), and endowed with the weak topology of $L_2(0, T; H_0)$. Then as $\varepsilon \rightarrow 0$, the solution u_{h_ε} of the stochastic controlled equation converges in distribution to the solution u_{h_0} of the controlled equation in $X = C([0, T]; H) \cap L^2((0, T); V)$, where for $\varepsilon \geq 0$: $u_{h_\varepsilon}(0) = \xi$ and

$$du_{h_\varepsilon} + [Au_{h_\varepsilon} + B(u_{h_\varepsilon}) + \tilde{R}(t, u_{h_\varepsilon})]dt = \sigma(u_{h_\varepsilon})h_\varepsilon(t)dt + \sqrt{\varepsilon} \sigma(u_{h_\varepsilon})dW(t)$$

Formulation of the LDP

Inviscid LDP

Let the **positive** viscosity coefficient $\nu \rightarrow 0$ and

$$d_t u^\nu(t) + [\nu A u^\nu(t) + B(u^\nu(t))] dt = \sqrt{\nu} \sigma(t, u^\nu(t)) dW(t), u^\nu(0) = \xi$$

Prove exponential decay of $P(u^\nu(\cdot) \in \Gamma)$ as $\nu \rightarrow 0$ for $\Gamma \subset Y$ that is

$$\lim_{\nu \rightarrow 0} \nu \ln P(u^\nu \in \Gamma)$$

in terms of some rate function and interior (resp. closure) of Γ for some **topology which is not the "optimal"** one

Why ? The rate function is formulated in terms of the **"irregular"** **inviscid case**, for h in the RKHS of the noise,

$$du_h^0(t) + B(u_h^0(t)) dt = \sigma(t, u_h^0(t)) h(t) dt, \quad u_h^0(0) = \xi$$

Requires some more hypothesis on σ with **Radonifying operators** (extend trace-class operators for **non Hilbert Sobolev spaces**)

One can **extend the stochastic calculus** (Itô's formula and BDG inequality) to Radonifying operators

Formulation of the LDP

Inviscid NS equations

Theorem

(Bessaih-M.) Let $\xi \in V$ satisfy $\operatorname{curl} \xi = \partial_1 \xi_2 - \partial_2 \xi_1 \in L^\infty(D)$, $\sigma \in C(V; L^q(H_0, V))$ be such that $\operatorname{curl} \sigma \in C(H^{1,q}; R(H_0, L^q(D)))$ with $q > 2$ satisfies "growth and Lipschitz conditions". Then as $\nu \rightarrow 0$, the distribution of the solution u^ν to
$$du_t^\nu + [\nu Au_t^\nu + B(u_t^\nu, u_t^\nu)] dt = \sqrt{\nu} \sigma(u_t^\nu) dW(t)$$
 with the initial condition $u_0^\nu = \xi$ satisfies in $\mathcal{X} = C([0, T]; L^q(D) \cap H)$ endowed with the norm $\|u\|_{\mathcal{X}} := \sup_{0 \leq t \leq T} |u_t|_q$ satisfies a LDP with the good rate function

$$I(u) = \inf \{ \|h\|_{L^2([0, T], H_0)}^2 / 2 : u = u_h^0, h \in L^2(0, T; H_0) \} \quad \text{and}$$

and u_h^0 is the unique solution to the control equation

$$du_h^0(t) + B(u_h^0(t), u_h^0(t)) dt = \sigma(u_h^0(t)) h(t) dt, \quad u_h^0(0) = \xi$$

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The "Stroock-Varadhan" theorem

The problem

Prove a "Stroock-Varadhan" theorem to characterize the support in $X = C([0, T]; H) \cap L^2([0, T], V)$ of the distribution of general 2D hydrodynamical models

$$du(t) + [Au(t) + B(u(t)) + Ru(t)] dt = \sigma(u(t)) dW(t), \quad u(0) = \xi \in H,$$

SPDE setting, for hyperbolic, wave, parabolic, Burgers, "mild solutions" in Hilbert spaces, similar results proved by Bally-M.-Sanz Solé, M.-Sanz Solé, Twardowska-Zabczyck, Cardon-Weber-M, Nakayama

Condition (R) Recall that $V \subset \mathcal{H} \subset H$

(i) $t \in [0, T] \mapsto \|u(t)\|_{\mathcal{H}}$ is continuous a.s.

(ii) there exists $q > 0$ such that for any constant $C > 0$ and

$$\tau_C := \inf \{ t : \sup_{s \leq t} |u(s)|^2 + \int_0^t \|u(s)\|^2 ds \geq C \} \wedge T$$

$$\mathbb{E} \left(\sup_{[0, \tau_C]} \|u(t)\|_{\mathcal{H}}^q \right) < \infty$$

Support theorem

characterization for hydrodynamical models

$\sigma : H \rightarrow L_Q(H_0, H)$, $(e_j, j \geq 1)$ CONS of H such that $Qe_j = q_j e_j$ with $\sum_j q_j = \text{Trace}(Q) < +\infty$, $\sigma_j : H \rightarrow H$ defined by $\sigma_j(u) := \sigma(u)e_j, \forall u \in H$

- For any j , σ_j twice (Fréchet) differentiable, with **bounded** derivatives.
- Stratonovich correction $\rho(u) = \sum_{j \geq 1} D\sigma_j(u) \sigma_j(u)$

Then if $\xi \in H$ and condition **(R)** holds, the **support of the distribution** of the solution u to

$$du(t) + [Au(t) + B(u(t)) + Ru(t)] dt = \sigma(u(t))dW(t), u_0 = \xi,$$

is the **closure in X** of $S(L^2([0, T], H_0))$ where $S(h)_0 = \xi$ and

$$dS(h)_t + [AS(h)_t + B(S(h)_t) + RS(h)_t] dt = \sigma(S(h)_t)h(t)dt - \frac{1}{2}\rho(S(h)_t)dt$$

Support Theorem

Wong-Zakai approximation

The support characterization follows from **one result of convergence in probability** of some general sequence of evolution equations **driven by W** , a **finite-dimensional, linear adapted time interpolation W^n of W** and an element **h of the RKHS of W** . (Mackevičius, Aida Kusuoka & Stroock and M. & Sanz-Solé for diffusion processes)

In general, condition (R) holds for $\mathcal{H} = Dom(A^{\frac{1}{4}})$ when:

$$|\sigma(u)|_{L^Q}^2 \leq K_0 + K_1|u|^2, \quad |\sigma(u) - \sigma(v)|_{L^Q}^2 \leq L|u - v|^2$$

$$|A^{\frac{1}{4}}\sigma(t, u)|_{L^Q(H_0, H)}^2 \leq K(1 + \|u\|_{\mathcal{H}}^2), \quad |A^{\frac{1}{4}}R(u)| \leq \bar{R}_0(1 + \|u\|_{\mathcal{H}}).$$

In first examples, condition (R) holds:

- for 2D Navier-Stokes equation on periodic domains with no restriction if $(B(u), Au) = 0$
- for Boussinesq or 2D MHD models for $\mathcal{H} = Dom(A^{\frac{1}{4}}) \subset L^4(D)$
- for GOY or Sabra shell models for $\mathcal{H} = Dom(A^s)$ and $0 \leq s \leq \frac{1}{4}$

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Stochastic 2D Euler equation

The result

$$d_t u(t) + [B(u(t), u(t)) + \nabla p]dt = f(t, u) + \sigma(t, u(t))dW_t$$

with $\operatorname{div} u = 0$ in D , $\langle u, n \rangle = 0$ on ∂D

Theorem

(Brzezniak-Peszat) Suppose that the noise $W(t, x)$ is space homogeneous with RKHS H_0 . Let $u_0 \in H^{1,q}$ for some $q > 2$,

$f : [0, T] \times H^{1,a} \rightarrow W^{1,a}$ for $a = 2, q$,

$\sigma : [0, T] \times H^{1,2} \rightarrow L_{\mathcal{H}\mathcal{S}}(H_0, W^{1,2})$ and

$\sigma : [0, T] \times H^{1,2} \rightarrow \text{Radonifying}(H_0, W^{1,q})$.

Then there exists a triple (Ω, W, u) such that W has the imposed spectral measure (related to the covariance structure) and $u(0) = u_0$, for every $p \in [1, \infty)$, $u \in L^p(\Omega; L^\infty(0, T; H^{1,2} \cap H^{1,q}))$ and $u(t)$ satisfies the stochastic Euler equation.

Stochastic 2D Euler equation

Comments

No smoothing effect of the Stokes operator: viscosity $\nu = 0$

Remarks:

- stronger conditions on initial condition and diffusion coefficient
- Weak probabilistic solution : prove tightness of approximations with a viscosity coefficient $\nu \rightarrow 0$
- Use again $\langle B(u, u), u \rangle = 0$ and the equation satisfied by $\operatorname{curl} u = \partial_1 u_2 - \partial_2 u_1$ with

$$\langle \operatorname{curl} B(u, v), \operatorname{curl} v |\operatorname{curl} v|^{q-2} \rangle = 0$$

for $u, v \in H^{2,q}$

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Stochastic 3D NS equations

The coercivity argument used in the identification fails.

Spatially homogeneous noise with diffusion coefficient on \mathbb{R}^3 and use some weighted $L^p(a)$ spaces (with $a > \frac{3}{2}$)

$$\|f\|_{L^p(a)}^p = \int_{\mathbb{R}^3} |f(x)|^p (1 + |x|^2)^{-a} dx$$

• Capinsky-Peszat: get rid on the pressure by "testing solution on appropriate functions" involving the weight. Give an initial distribution on $L^2(a)$ and prove the existence of a triple (Ω, W, u) such that for $a > \frac{3}{2}$, there exists a solution $u \in L^p(\Omega, L^\infty(0, T; L^2(a)))$

They approximate the solution by an auxilliary equation u^ϵ and prove tightness

$$\begin{aligned} d_t u^\epsilon + \left[-\Delta u^\epsilon + B(u^\epsilon, u^\epsilon) + \epsilon |u^\epsilon|^4 u^\epsilon - \frac{1}{\epsilon} \nabla \operatorname{div} u^\epsilon \right] dt \\ = f(t, u^\epsilon) dt + \sigma(t, u^\epsilon) dW(t) \end{aligned}$$

Stochastic 3D NS equations

- Basson has an **additive divergence free noise homogeneous noise** on $L^2(r)$ with $r > \frac{3}{2}$ and an initial spatially homogeneous distribution on $L^2(r)$ with null divergence.

He approximates by periodic solutions (proving the tightness)

He solves first the equation $d_t z(t) = \Delta z(t)dt + W(t)$ (which is divergence free) and then uses deterministic estimates for

$$d_t v(t) - \Delta v(t)dt + B(v(t) + z(t), v(t) + z(t))dt + \nabla p = 0$$

He proves energy estimates involving the pressure for a solution $u \in \cap_{b>3} L^\infty(0, T; L^2(b)) \cap L^2(0, T; H^{1,2}(a))$ for $b > \frac{3}{2}$